

# Nathan Dunkelberger

nathandunkelberger.com – 7300 Brompton St - Houston, Texas 77025 – (832) 766-8510 – nbd2@rice.edu

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## Education

- Rice University**, Houston TX May 2022  
PhD in **Mechanical Engineering**  
Advisor: Dr. Marcia O'Malley  
Overall GPA – 4.0
- Texas A&M University**, College Station, TX May 2017  
Bachelors of Science in **Mechanical Engineering**  
Overall GPA – 3.81
- Spain Study Abroad**, Ciudad Real, Spain Summer 2015
- Studied two mechanical engineering courses in Spain, visiting nine cities and two countries
  - Stayed with a host family from Spain and was introduced to many local experiences

## Experience

- Integration of Functional Electrical Stimulation and Exoskeletons**, Houston, TX Summer 2017-Present
- Performed pilot tests verifying the potential benefits of combining the two rehabilitation techniques
  - Worked in collaboration with Cleveland State University
- Multi-sensory Haptic Communication Device Design**, Houston, TX Summer 2017-Present
- Designed a device for Haptic communication consisting of 3 haptic modalities
  - Developed a user interface and test setup for many user studies
  - Performed subject tests using our device where subjects understood language in 100 minutes of training
  - Developed scripts to analyze and visualize collected data to present in weekly meetings
- AggiE-Challenge Exoskeleton for Stroke Rehabilitation**, College Station, TX Fall 2016-Spring 2017
- Developed an innovative exoskeleton to improve stroke rehabilitation as an undergraduate research assistant
  - Participated in a team developing an augmented reality environment to better engage the user
  - Participated in a team electromechanically integrating the exoskeleton
  - Developed written and visual representations of work for internal presentations
- Mechanical Engineering Senior Design Project**, College Station, TX Fall 2016-Spring 2017
- Developed a system to mark pipes in the manufacturing process given input parameters as a part of a team of four senior mechanical engineers
  - Worked in close contact with a representative from Tenaris, building communication and project management skills
- Biomechanical Environments Lab Research**, College Station, TX Spring 2016-Spring 2017
- Assisted in development of an adaptable load frame for biomechanical testing
  - Conducted research on a novel Total Knee Replacement product as an undergraduate research assistant
  - Mentored an undergraduate for the development of a device for physiological testing
  - Disseminated knowledge via website, conferences, and internal laboratory presentations
- Temperature Regulating Shower Valve Mechatronics Project**, College Station, TX Fall 2016
- Designed a shower valve which regulated water temperature given two input valves
  - Utilized used a real-time PID controller with an Arduino to regulate temperature
- Undergraduate Summer Research Grant**, College Station, TX Summer 2016
- Improved a modular simulation device for physiological testing as an undergraduate research assistant
  - Developed and carried out protocol to validate and improve the simulator
  - Mentored underrepresented high school students and supervised their experience with research
  - Produced draft of an article for submission to peer-reviewed Journal of Biomechanical Engineering
  - Gained a deeper understanding of professional development and graduate school through seminars
- AggiE-Challenge Research**, College Station, TX Fall 2015-Spring 2016
- Participated in a team of 5 interdisciplinary engineering undergraduate students

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- Conducted research in 3D printing cancer-mimicking models with the goal of improving the accuracy of medical testing
- Presented findings as a poster at Texas A&M's Engineering Project Showcase

**Formula SAE Racecar Modeling Project**, College Station, TX Spring 2015

- Used dynamic models to predict the behavior of a racecar
- Produced graphs showing the relationship between displacement, velocity, and acceleration for several points of interest of the racecar with varying degrees of freedom on different vehicle paths

**Club Z! Tutoring**, Houston, TX Summer 2014

- Tutored two students in algebra and geometry to prepare for the next year of classes
- Gained one on one communication skills

**Halliburton High School Summer Externship**, Houston, TX Summer 2013

- Worked with several different departments on daily activities and projects
- Participated in company meetings and projects

**National Oilwell Varco High School Summer Externship**, Houston, TX Summer 2012

- Learned about daily activities of many different employees
- Completed company workshops
- Worked in several different parts of a company warehouse

## Relevant Coursework

- Analysis & Control of Nonlinear Systems
- Algorithmic Robotics
- Robotics
- Dynamics & Modeling of Mechatronic Systems
- ML from Sensor Data
- Mechatronics

## Awards and Leadership

<b>Texas Space Grant Consortium Fellow</b> , NASA	Fall 2018
<b>Honorable Mention</b> , NSF GRFP	Spring 2018
<b>Eagle Scout</b> , Boy Scouts of America	2013
<b>Treasurer</b> , Percussion Studio	Fall 2015-Spring 2017
<b>International Engineering Certificate</b> , Texas A&M University	Summer 2016
<b>Deans Award</b> , Mechanical Engineering	Fall 2013-Fall 2017
<b>2<sup>nd</sup> Place Undergraduate Research Poster</b> , Student Research Week	Spring 2016
<b>1<sup>st</sup> Place Research Video</b> , AggieE-Challenge Research Video Contest	Fall 2015

## Poster Presentations and Publications

- **Nathan Dunkelberger, Sullivan, Jennifer, et al.** "Conveying Language Through Haptics: A Multi-sensory Approach", International Symposium on Wearable Computing ISWC. (2018) Singapore
- **Nathan Dunkelberger, Joshua Bradley, et al.** "Improving Perception Accuracy with Multi-sensory Haptic Cue Delivery" Eurohaptics, (2018) Pisa, Italy
- **Nathan Dunkelberger, Joshua Bradley, et al.** "Improving Perception Accuracy with MISSIVE: A novel, compact, wearable device for rendering multi-modal haptic sensations" Haptics Symposium, (2018) San Francisco, California
- **Derek Wolf, Nathan Dunkelberger, et al.** "Combining Functional Electrical Stimulation and a Powered Exoskeleton to Control Elbow Flexion" International Symposium on Wearable and Rehabilitation Robotics, Houston, Texas
- **Nathan Dunkelberger, Amanda Bass.** "Orthopedic Robots: Dog's Best Friend" *Texas A&M Explorations*, Volume 9 (2017) College Station, Texas
- **Rana Soltani, Amin Zeiaee, Nathan Dunkelberger, et al.** "Dynamics and Controls of an Upper Limb Exoskeleton" Texas A&M Engineering Project Showcase (2017) College Station, Texas
- **William Nelson, David Ramos, Nathan Dunkelberger, et al.** "Automated Pipe Marking System" Texas A&M Engineering Project Showcase (2017) College Station, Texas

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- **Nathan Dunkelberger**, Steve Zambrano, W. Brian Saunders, et al. “Evolution and Performance Validation of the Joint Motion Simulator (JMS)” Pathways Research Symposium (2016) Prairie View, Texas
- **Nathan Dunkelberger**, Steve Zambrano, W. Brian Saunders, et al. “Evolution and Performance Validation of the Physiologically Relevant Instrument for Mechanical Evaluation (PRIME)” MEEN Kickoff Poster Competition (2016) College Station, Texas
- **Nathan Dunkelberger**, Steve Zambrano, W. Brian Saunders, et al. “Evolution and Performance Validation of the Physiologically Relevant Instrument for Mechanical Evaluation (PRIME)” College of Engineering Research Symposium (2016) College Station, Texas
- Zachary Lawson, Sarah Chaudhri, **Nathan Dunkelberger**, et al. “In Vitro Mechanical Studies of Implantable Truss Technology for Total Knee Arthroplasty Designs” Student Research Week Symposium (2016) College Station, Texas
- Kedar Balakrishna, Sarah Dang, **Nathan Dunkelberger**, et al. “Development of 3D-Printed Vascularized Tumor Models” Texas A&M Engineering Project Showcase (2016) College Station, Texas

## Software, Coding, and other Skills

- Proficient SolidWorks
- Proficient C++
- Proficient Matlab
- Proficient Python
- Proficient 3D printing
- Proficient Microcontrollers
- Proficient C#
- Proficient Labview
- Basic Spanish
- Basic Simulink
- Basic Machining
- Proficient Unity